INDUSTRIAL ROBOTS



The close integration and synergy of mechanical engineering and electronic control technologies gave birth to **our** industrial robots. All the experience in design and production technologies acquired over its long history as a machine builder is reflected in its high-class machines and the controllers that drive them.

A line-up of three categories of robots each ranging from compact to large has been established.

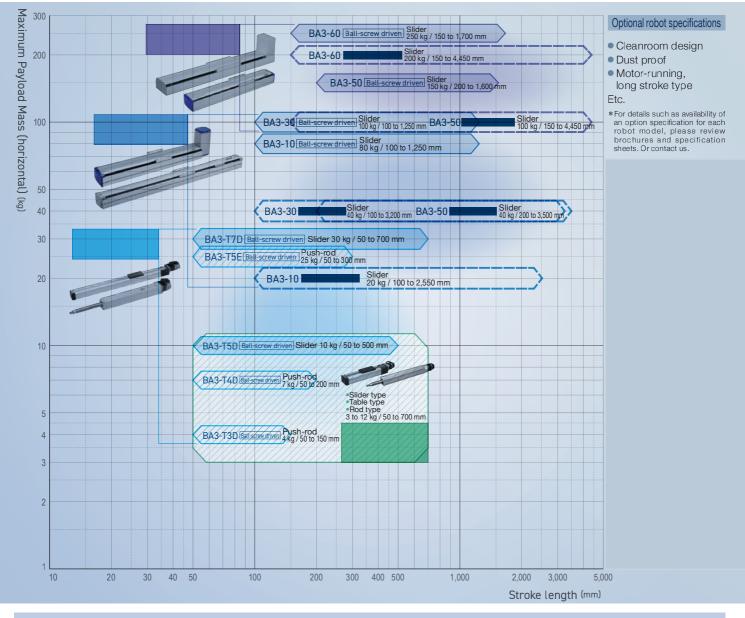
They help to provide the optimized industrial automation solutions,

resulting in increased productivity, and labor and cost reduction.



Cartesian Coordinate Robots

Reliable and agile Cartesian robots with flexible and varied configurations to meet factory floor needs



Typical Examples of Cartesian Axes Specifications



Number of axes	2 axes	2 axes	
Coordinate type	X-Y combination	X-Z combination	



Number of axes	2 axes	2 axes	
Coordinate type	Z-Y combination	Y-Z combination	



4 axes

Slave unit

Slave unit

Coordinate type	X-Y-Z combination		X-Y-Z-R combination	
Controller				
Model	CA25-M10	CA25-M40 CA25-M80	CA25-S10	CA25-S40 CA25-S80

3 axes

Main controller options

Number of axes

Туре

Additional I/O signals

Master unit

 Field network connectivity 			
	CC-Link Ethernet/IP	DeviceNet	

Master unit